

A Visual Analysis of the Relationship between Word Concepts and Geographical Locations

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and Video Retrieval (ACM CIVR)
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“Sushi” in Caltech 256



■ (Probably) Collected in **English** keywords

“Sushi” in our own dataset



■ Collected in **Japanese** keywords

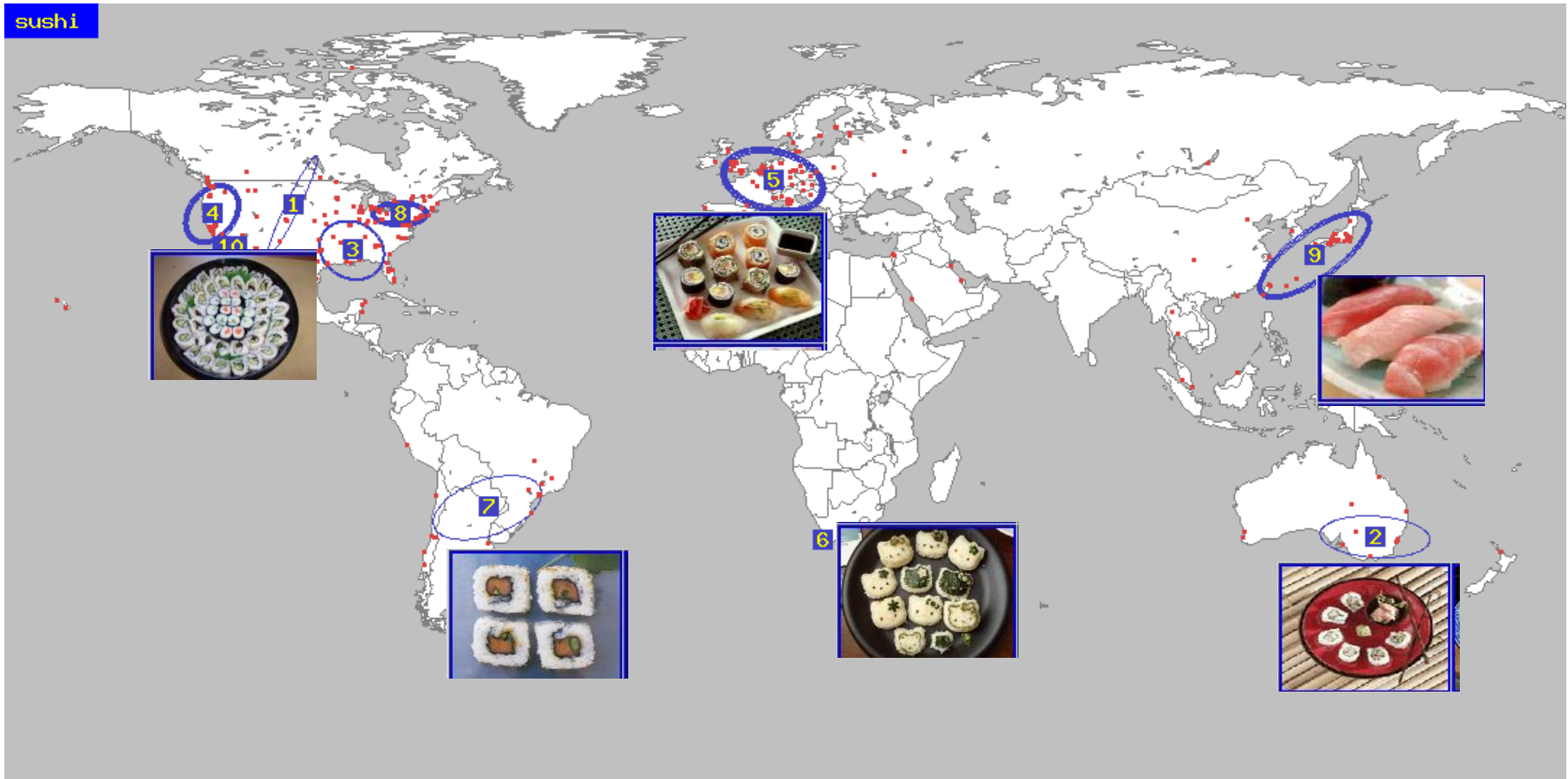
Which do you like to eat ?



Caltech “sushi”

Japanese “sushi”

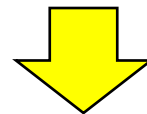
“Sushi” over the world



- **Image sets corresponding to the same concept are changing depending on locations or cultures.**

Questions about concepts and locations (or culture)

- **From this observation, representative image sets associated with a given concept might change (slightly) depending on locations or cultures.**



Questions?

- **Which concepts are location-dependent ?**
- **Which concepts are global (unchanged) over the world ? (e.g. “sea”, “sky”)**
- **How concepts change depending on locations ?**

“Sea” : *global concept*



The Aegean sea



The Japanese sea

***1. Objective,
Background
& Related work***

Objective of this paper

- **Analyze the relationship between word concepts and locations using geotagged photos on Flickr**
- **Consist of two parts:**
 1. **Entropy-based analysis**
 2. **A system to detect “cultural differences”**

They are relatively independent.

Background: geotagged photos

- The number of **geotagged photos** on the Web grows rapidly: Flickr, panoramio
 - Flickr has **100,000,000 geotagged photos**.
(Feb. 2009)



A “geo-tag” represents the coordinates (latitude, longitude) of a location where a photo are taken.

Related work: Geotagged image

Many work used geotags to organize *landmark photos*.

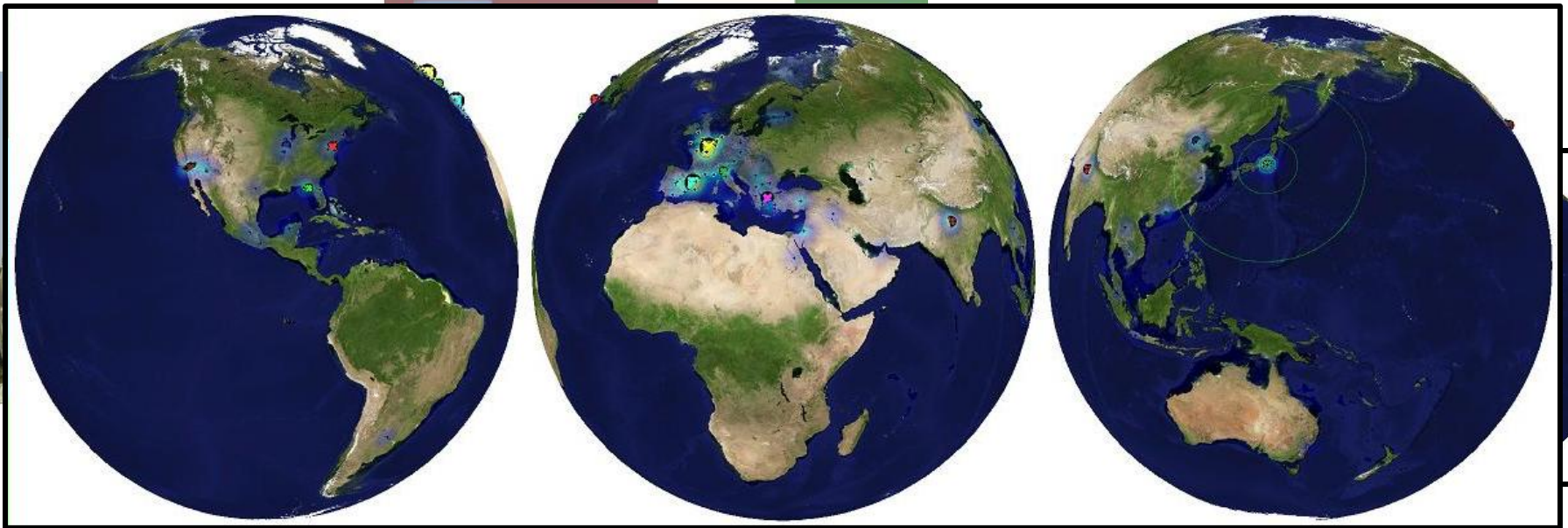
- Toyama et al. (2003)
- Jaffe et al. (2006)
- Simon et al. (2007)
- Kennedy et al. (2008)

..... and other many works.

The exception is “IM2GPS” [Hayes et al. 2008] among works on geotagged photos using image analysis.

Related work: “IM2GPS” [Hayes et al. 08]

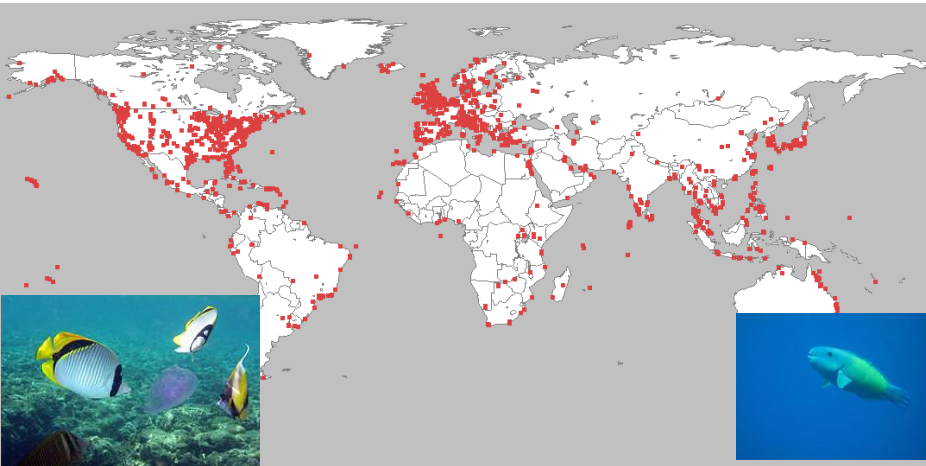
- Estimate the probability distribution over the world by nearest neighbor search for large-scale geotagged image DB. (ignoring “concepts”)



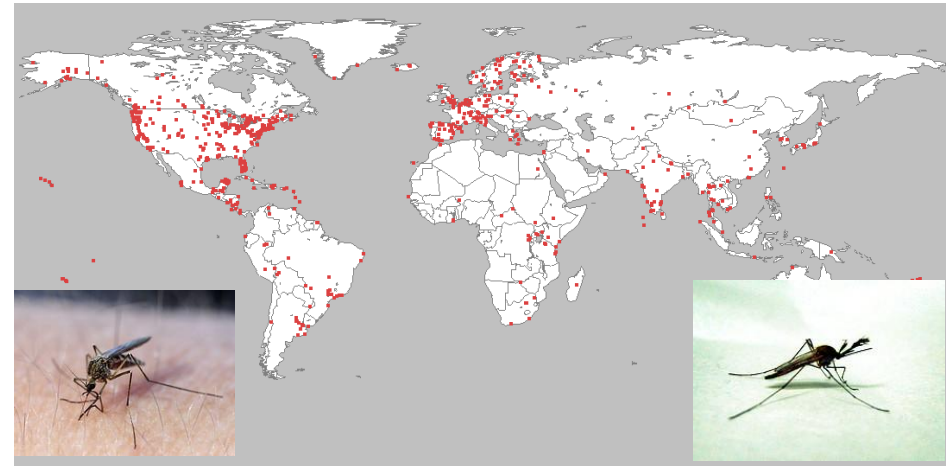
- This work suggests there exists the relation between visual features and geo-locations.

There are many non-landmark geotagged photos in Flickr !

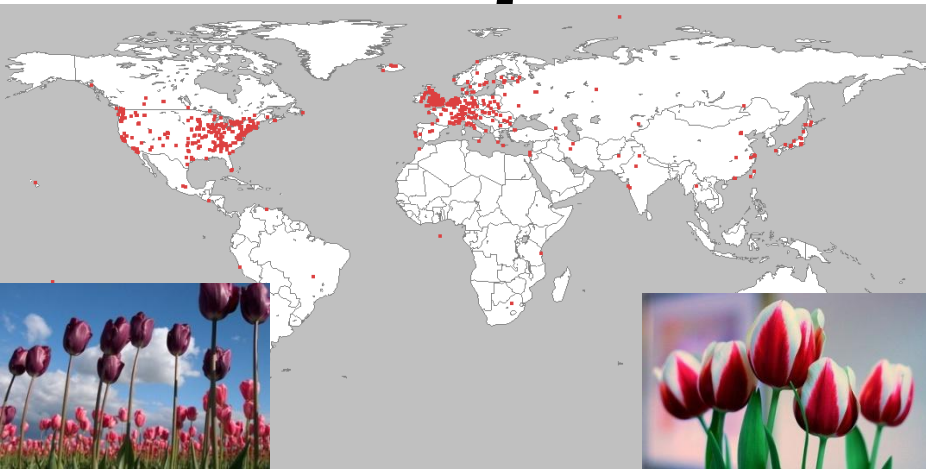
fish



mosquito



tulip



Deutschland



2. [Part 1]

Entropy-based analysis

Entropy-based analysis

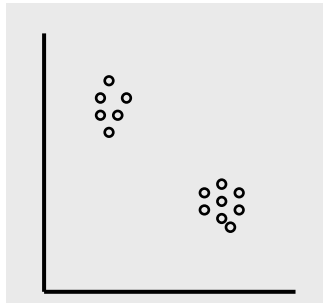
Examine the relation between distributions of visual features and geo-locations for many concepts

- 1. Entropy-based measure of visual features
(Modified method of [Yanai and Barnard 05])**
- 2. Entropy-based measure of geo-locations**
- 3. Analysis the relation between two kinds of entropy**
 - For 230 nouns**

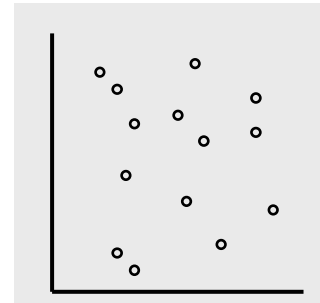
Image region entropy

[Yanai and Barnard 05]

- **A measure of “visualness” of words** (concepts)
- **Represent the property of the distribution of image region features**



Biased / uneven:
low entropy
having “visualness”



Random/uniform:
high entropy
not having “visualness”

**“Low entropy” means the concept has visual property,
“High entropy” means the concept has less visual
property.**

Low entropy: **“scary”** [Yanai and Barnard 05]



“Visual” concept

**Detected
“scary”
regions**

High entropy: “famous”

[Yanai and Barnard 05]



0.809 0.779 0.360



0.801 0.223 0.170 0.065 0.045



0.798 0.784 0.775 0.760 0.275 0.205



0.796 0.131



0.793 0.108



0.789 0.598 (1.000)



0.785 0.187 0.149



0.777 0.071



0.776 (1.000)



0.766 0.566



0.762 0.143 (1.000)



0.754 0.595 0.422 0.379 (1.000)



0.732



0.709 0.187 (1.000)



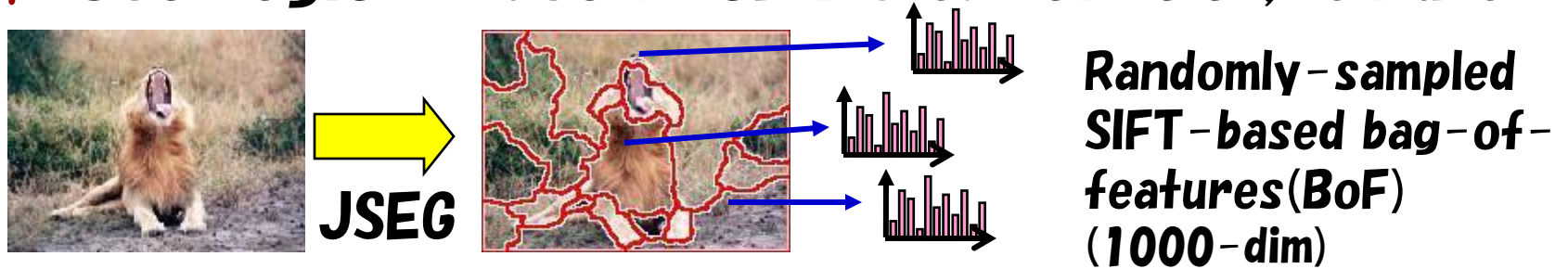
0.700

“Non-visual” concept

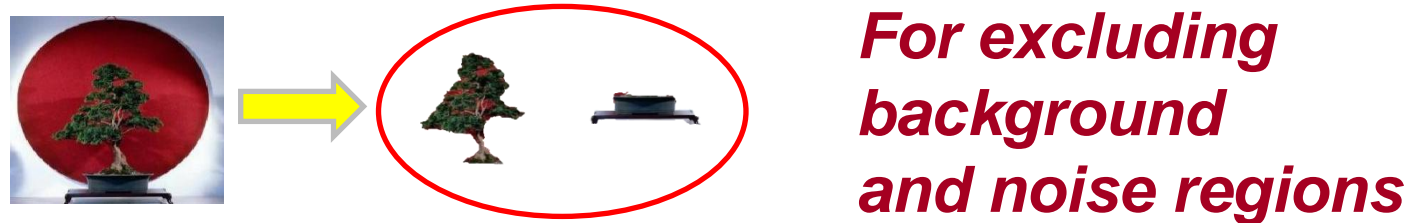
Modified image region entropy

■ Follow “image region entropy” [Yanai et al. 05]

1. Use region-based BoF *instead of color, texture*



2. Use mi-SVM to select relevant regions

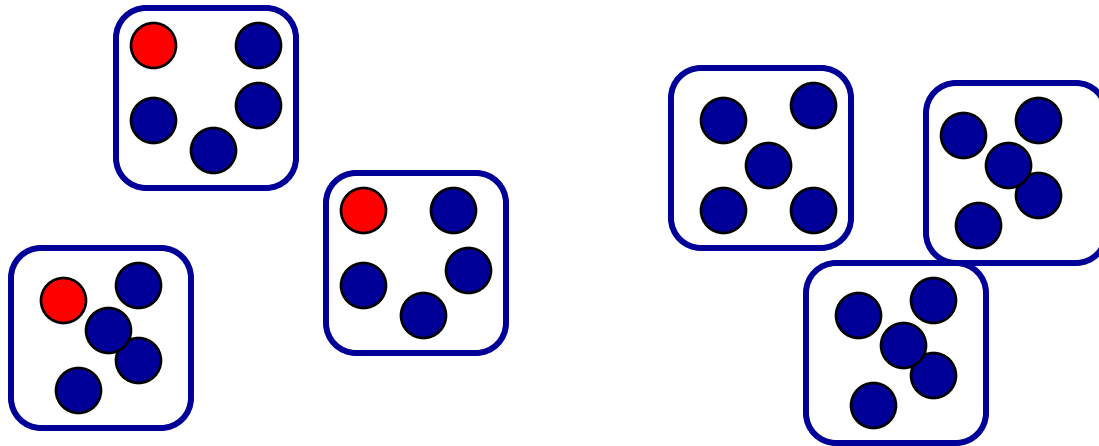


3. Model the distribution of region-based BoF vectors with pLSA *instead of GMM*

4. Calculate entropy based on pLSA vectors

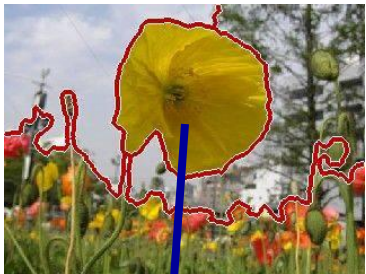
Multiple Instance Setting

■ Positive bags / Negative bags



● **positive ins.**
(foreground)

● **negative ins.**
(background)



Positive instances of "flower"

The rest of regions are
negative regions.

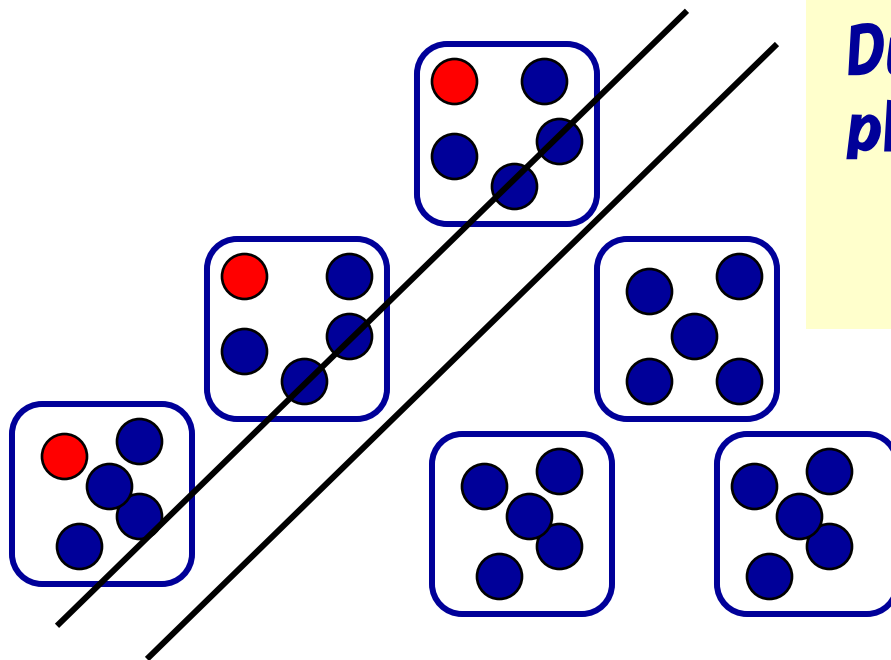
pseudo-training images

random images

mi-SVM

[Andrew et al. NIPS 03]

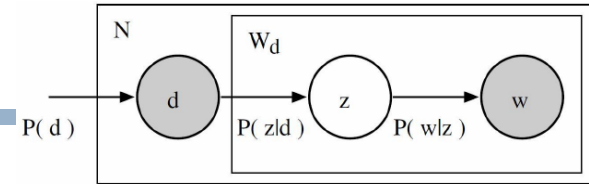
- **Apply soft-margin SVM iteratively**
 - **Training → classifying → training → classifying → …… (repeat 5 times)**



During the iteration, the hyper-plane is approaching the optimal plane to discriminate positive instances from negative ones.

- **positive ins. (foreground)**
- **negative ins. (background)**

Distribution modeling with the PLSA topic mixture 28



$$P(w, d) = P(d) \sum_z p(w | z) P(z | d)$$

w : visual words, d : regions, z : topic

① **Apply PLSA for all the regions of all the random (background) images in advance**

➔ **Obtain $P(w | z)$ and fix it (based distribution)**

10,000 random Web images



② **Estimate $P(z | d)$ for each regions with fixed $P(w | z)$ using fold-in heuristic [Hofmann 09]**

Calculate image region entropy

- **$H(X)$: entropy of the given word “X”**

$$H(X) = - \sum_k P(z_k|X) \log_2 P(z_k|X)$$

$$P(z_k|X) = \frac{1}{I} \sum_i P(z_k|d_i^X)$$

- **$H(X)$ can be calculated from each of 5 iterations of mi-SVM**



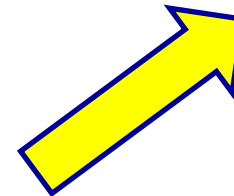
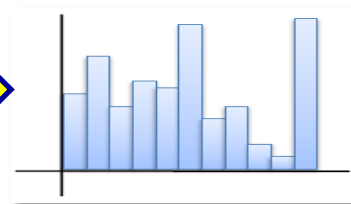
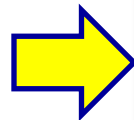
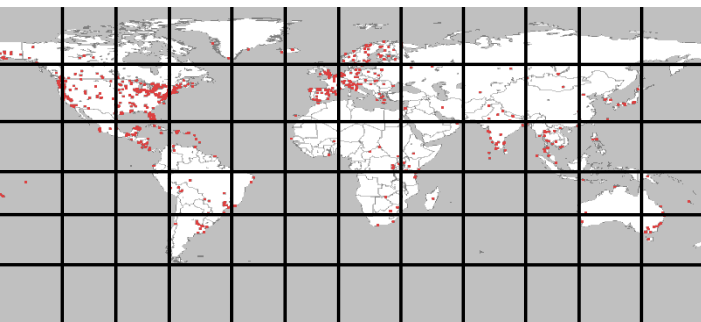
- **Regard the minimum $H(X)$ during 5 iterations as the final entropy $H(X)$**

Calculate geo-location entropy

- 1. Divide the world into 4 kinds of grids with every 10 degrees by shifting 5 degrees in terms of both latitude and longitude**
- 2. Build histograms regarding the geotags of the selected regions**
- 3. Calc entropy**
- 4. Select minimum one**

Geo-location entropy

$$H_{geo}(X) = - \sum_i b_i \log_2 b_i$$



**3. [Part 1] Results of
entropy-based
analysis**

Experiments

■ Data

- **230 nouns including various kinds of words**
 - Gathered photos including the given nouns as their tags
- **500 geotagged photos at least / each tag from Flickr**
(limiting 5 photos for each tag per user ID)





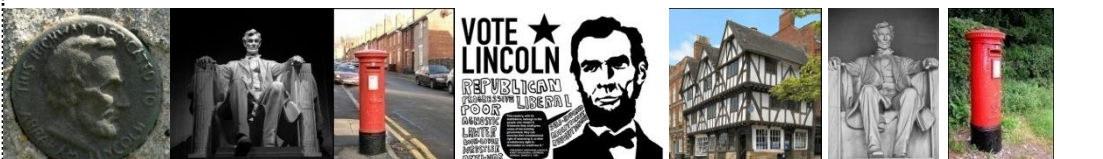

- **After selecting relevant regions for each tag, calculate the two entropy:**

Image region entropy $H_{\text{vis}}(\mathbf{X})$

Geo-location entropy $H_{\text{geo}}(\mathbf{X})$

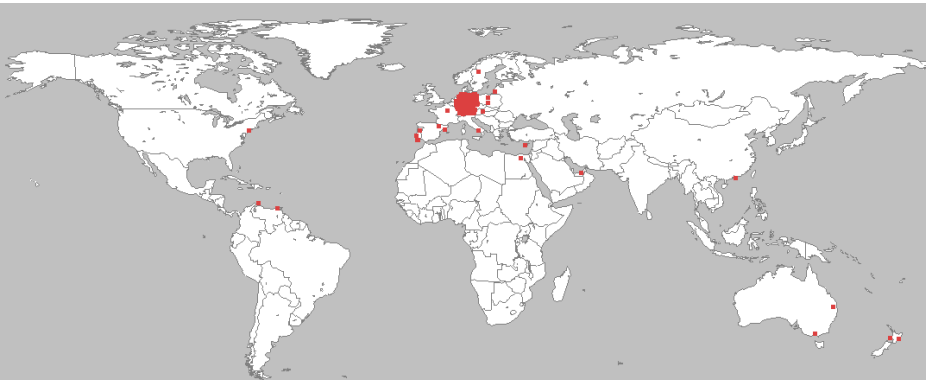
- **Analyze relation between them**

Image region entropy $H_{vis}(X)$

sun	3.6497	
rainbow	4.5538	
moon	4.6686	
mozart	7.8349	
lincoln	7.7327	
school	7.6173	

Geo-entropy $H_{geo}(X)$

Deutschland



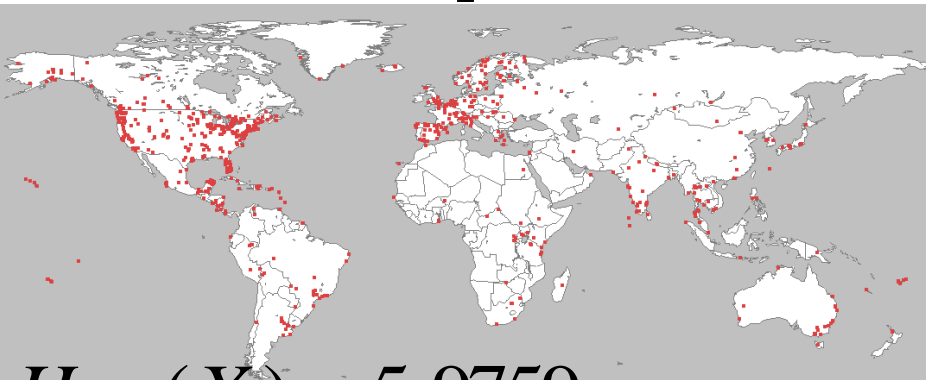
$$H_{geo}(X) = 0.2602$$

Rome



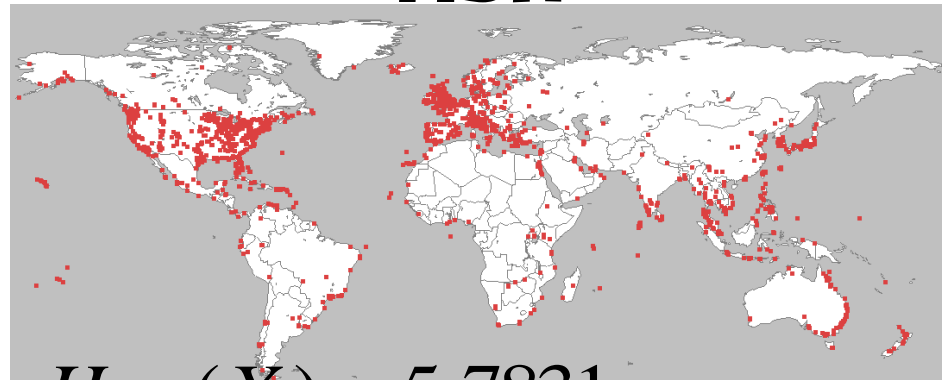
$$H_{geo}(X) = 0.3843$$

mosquito



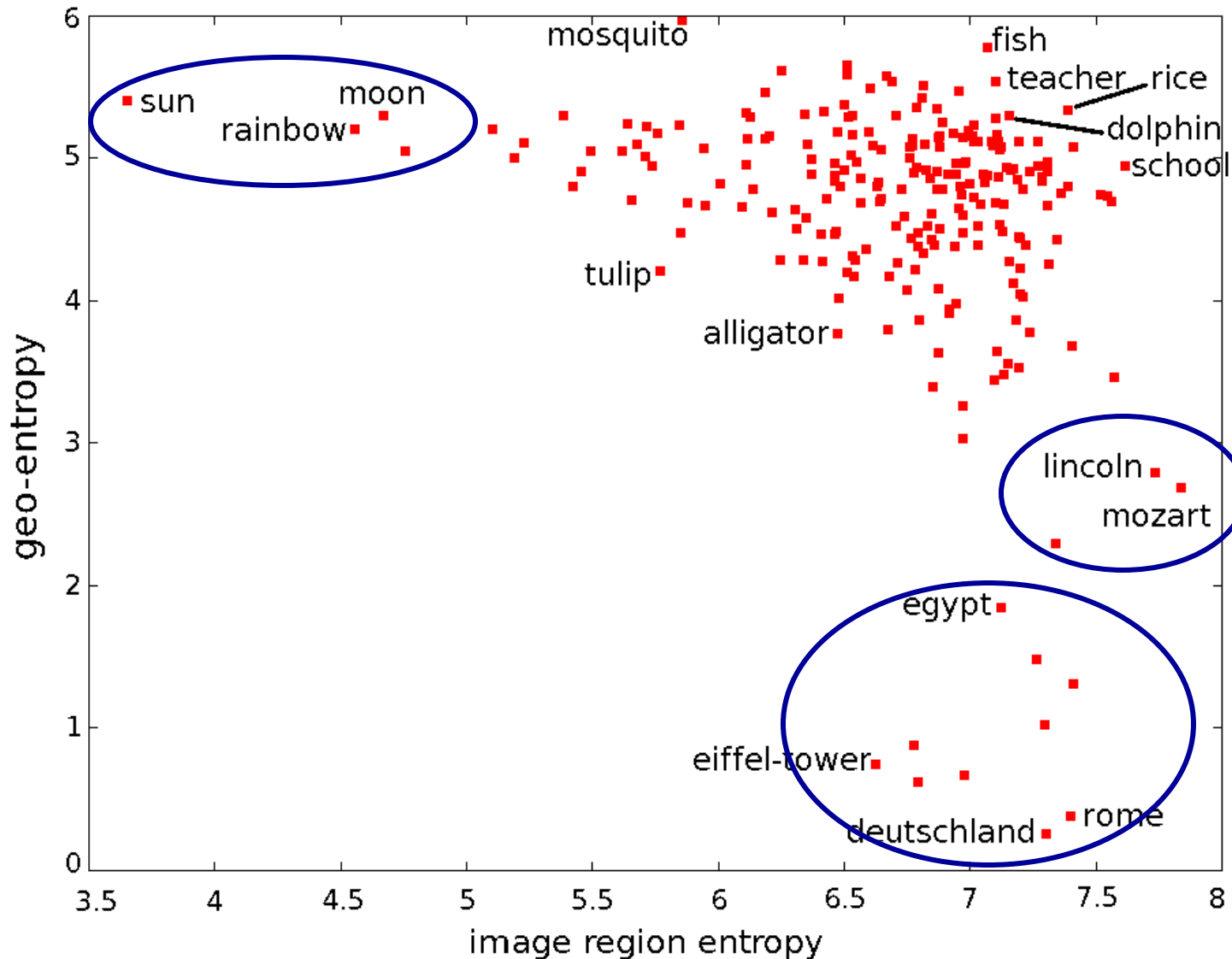
$$H_{geo}(X) = 5.9759$$

fish

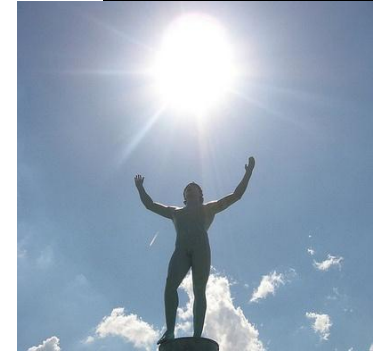


$$H_{geo}(X) = 5.7831$$

Image entropy vs. geo-entropy



Sun, rainbow, moon

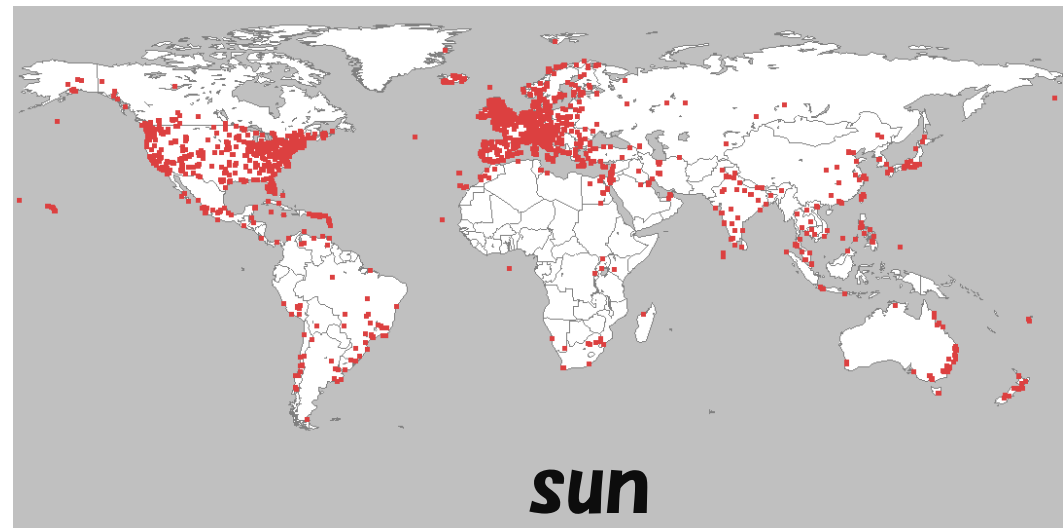
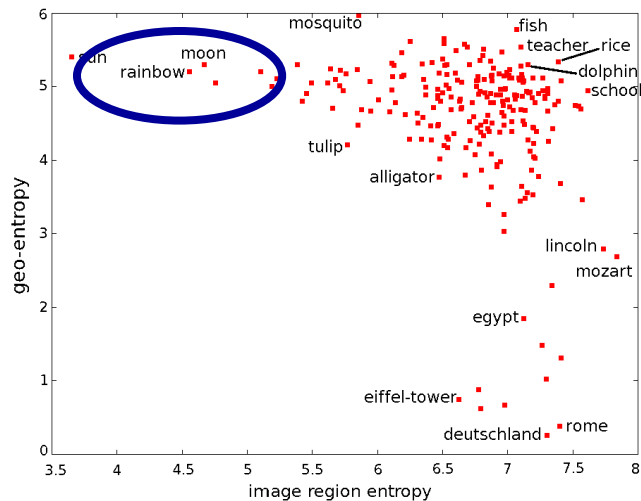


- **Concepts related to sky**

- **Image region entropy : low**

- **Geo-location entropy : high**

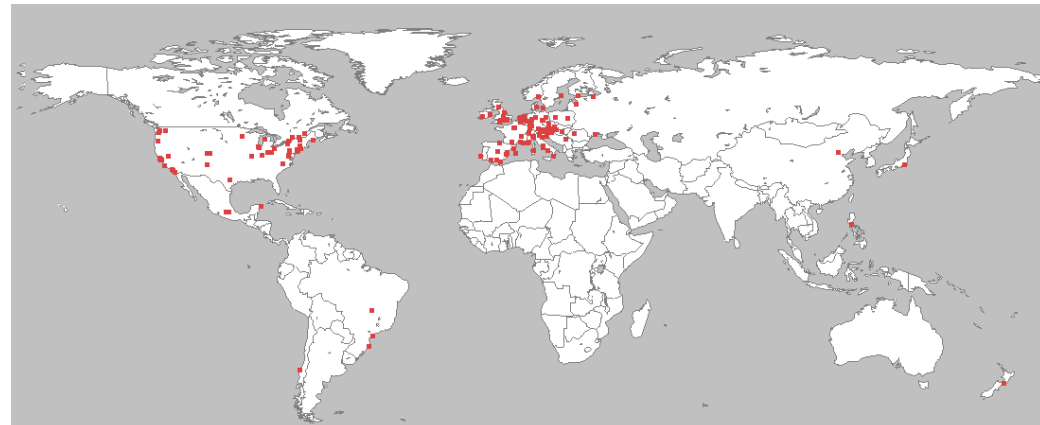
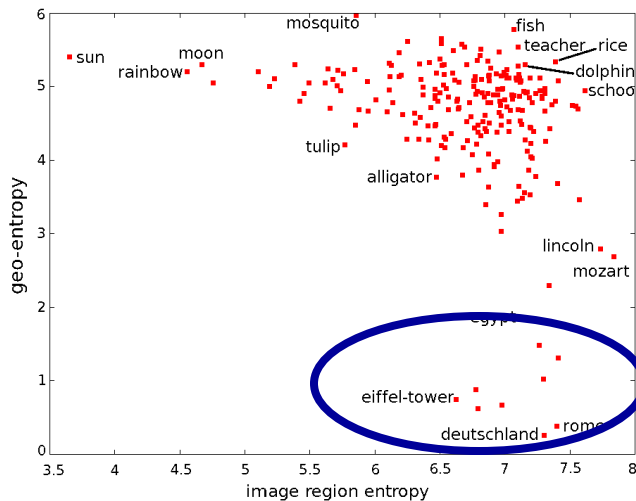
**They exist everywhere in the world,
and the appearances are similar.**



Rome, Deutschland, Mozart

- **Image region entropy: high**
- **Geo-location entropy : low**

The geotags concentrates on specific areas. Their appearances are various.



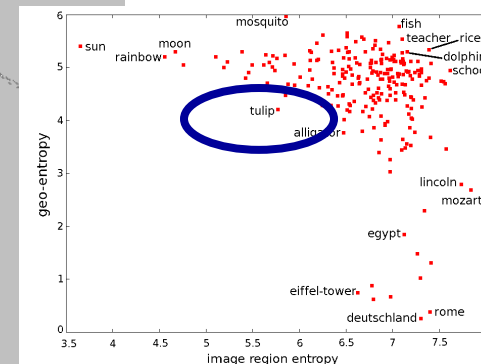
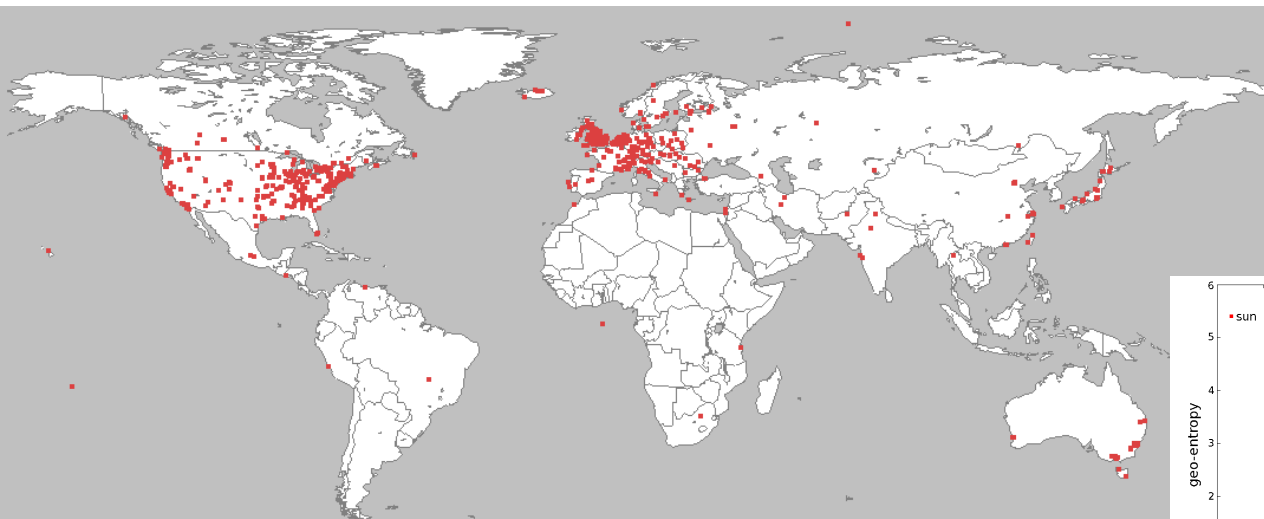
mozart

tulip

Image region entropy: low
Geo-location entropy : med.



- Variance of color did not reflect on image region entropy, since we use SIFT-based BoF representation.
- Holland and England are main areas.

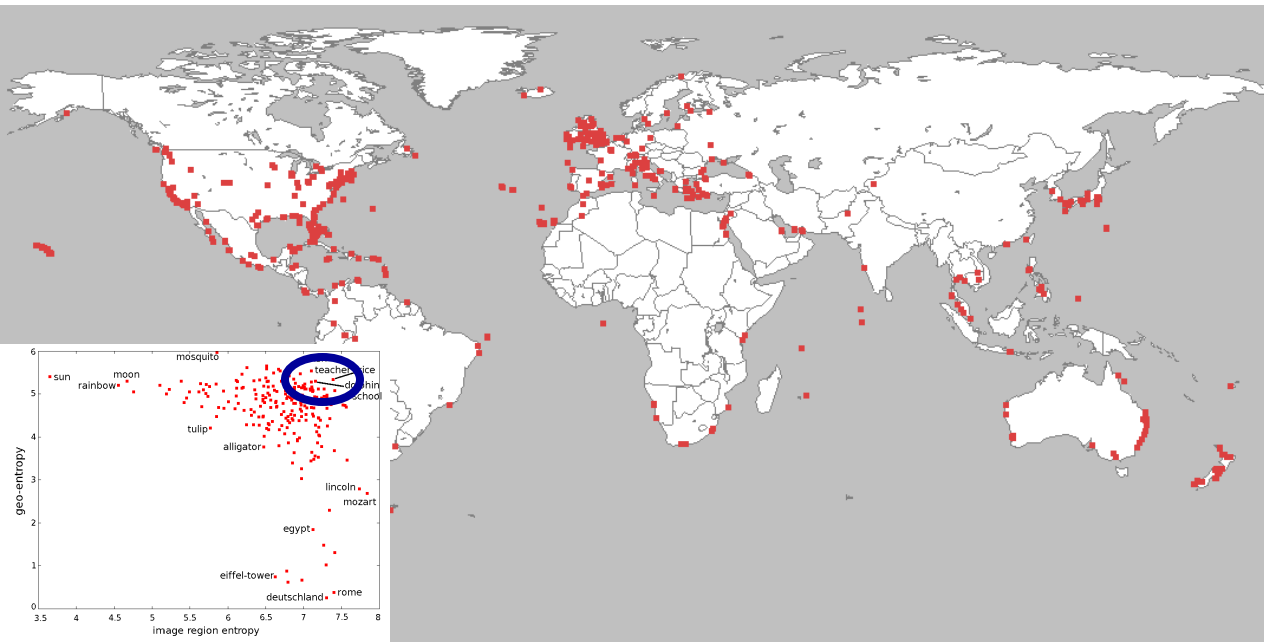


dolphin

Image region entropy: high
Geo-location entropy : high

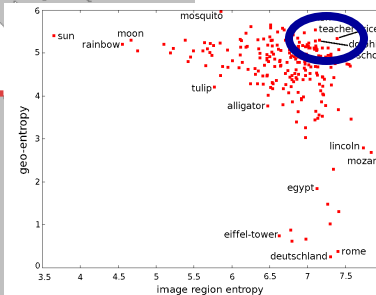
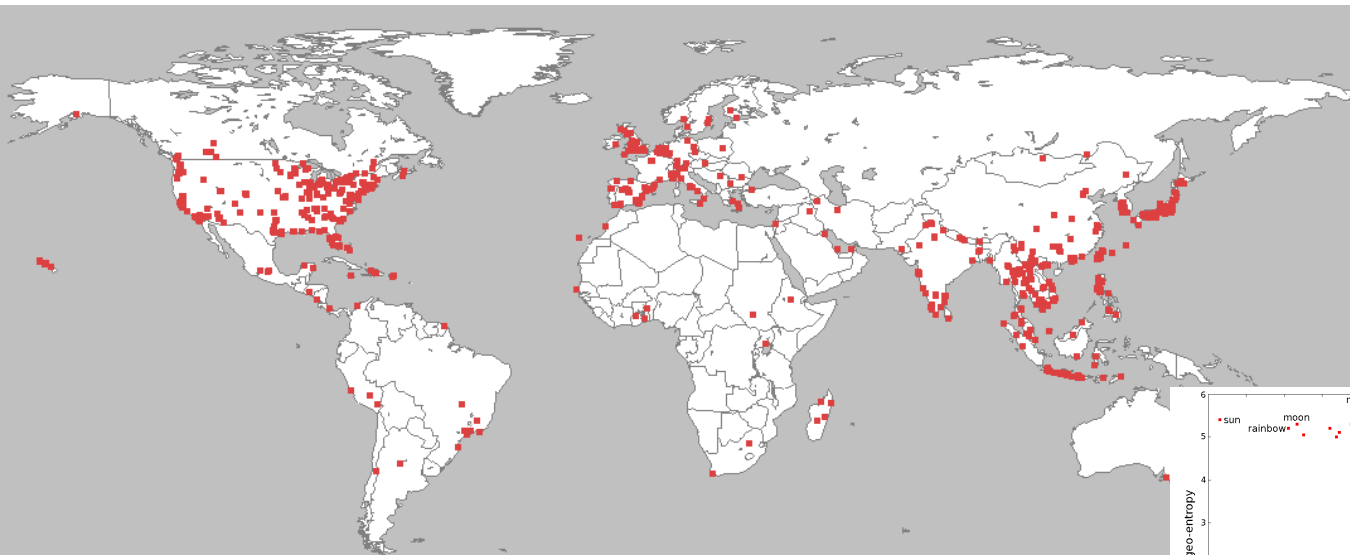
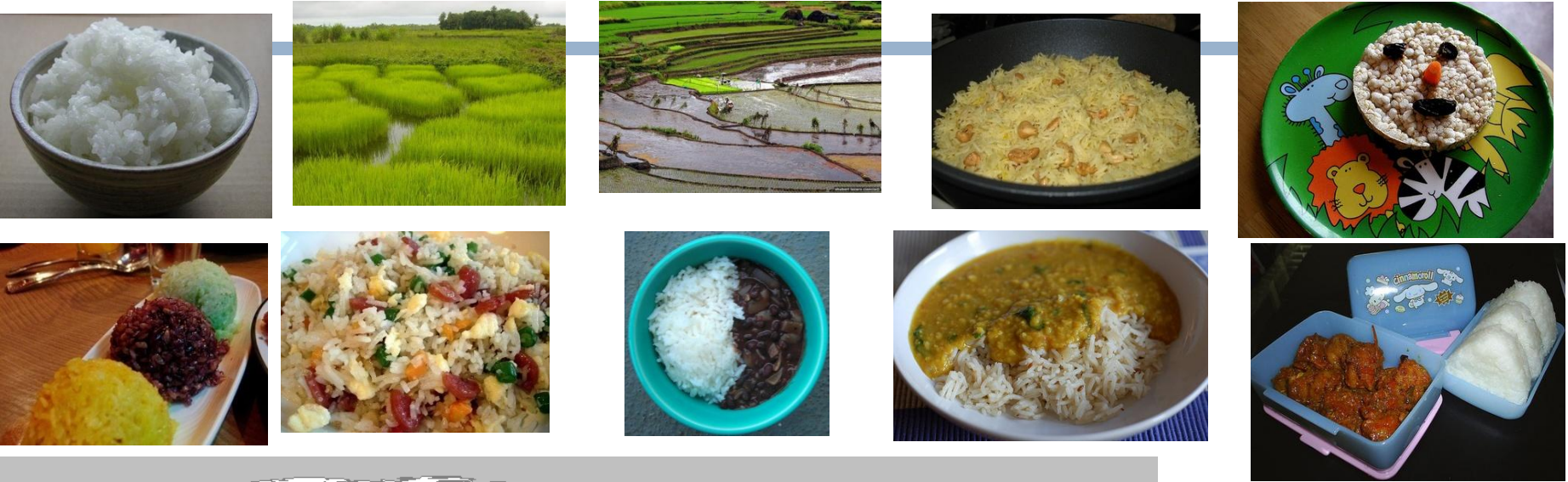


- Most of dolphins are taken in sea or aquarium
- In seaside areas over the world



rice

Image region entropy: high
Geo-location entropy : high

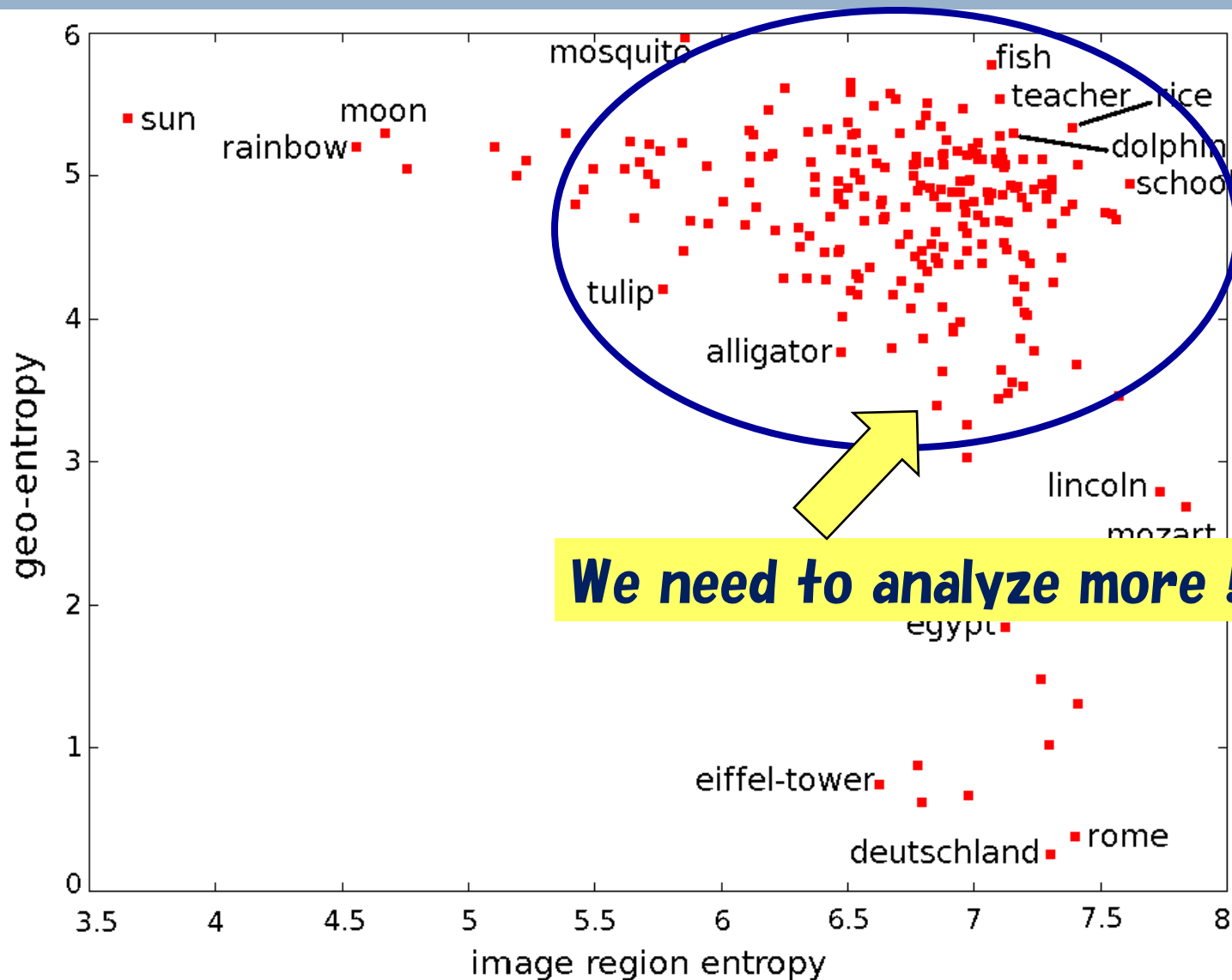


$$H_{geo}(X) = 5.3425$$

4. [Part 2]

***Discovering concept
differences in terms
of location***

Image entropy vs. geo-entropy



Objective of the second part

Utilize the set of geo-tagged photos on **Flickr**

- **A system to mine representative photos for representative areas or regions from geotagged photo DB.**



Raw geo-tagged photos on Flickr



Relevant photos after noise image removal



Representative photos for typical regions

Motivation : Foods over the world

- So with such geotagged photos, we can **discover specific objects over the world.**

- ✓ Do you know all kinds of famous **"noodles"** in the world?

- ✓ "Ramen" and "Soba" in Japan, "Thai noodle" in Thailand, "Chinese noodles", "rice noodle" Taiwan, "Spaghetti" in Italy...



As a result, we can discover cultural differences on specific concepts over the world !

"clothes" , "car" , "sushi"

Approach : three steps

1) Select relevant photos and remove noise

- ✓ Extract BoF vectors from all the images
- ✓ Visual clustering with k-means
- ✓ Select most relevant clusters based on the size of clusters

2) Detect representative regions

- ✓ Clustering based on geographic locations by k-means

3) Generate representative photo sets for representative regions

- ✓ Generate the PLSA topic vectors
- ✓ Aggregate photos according to the distribution of mixture topics and rank photos for each representative area

Contributions

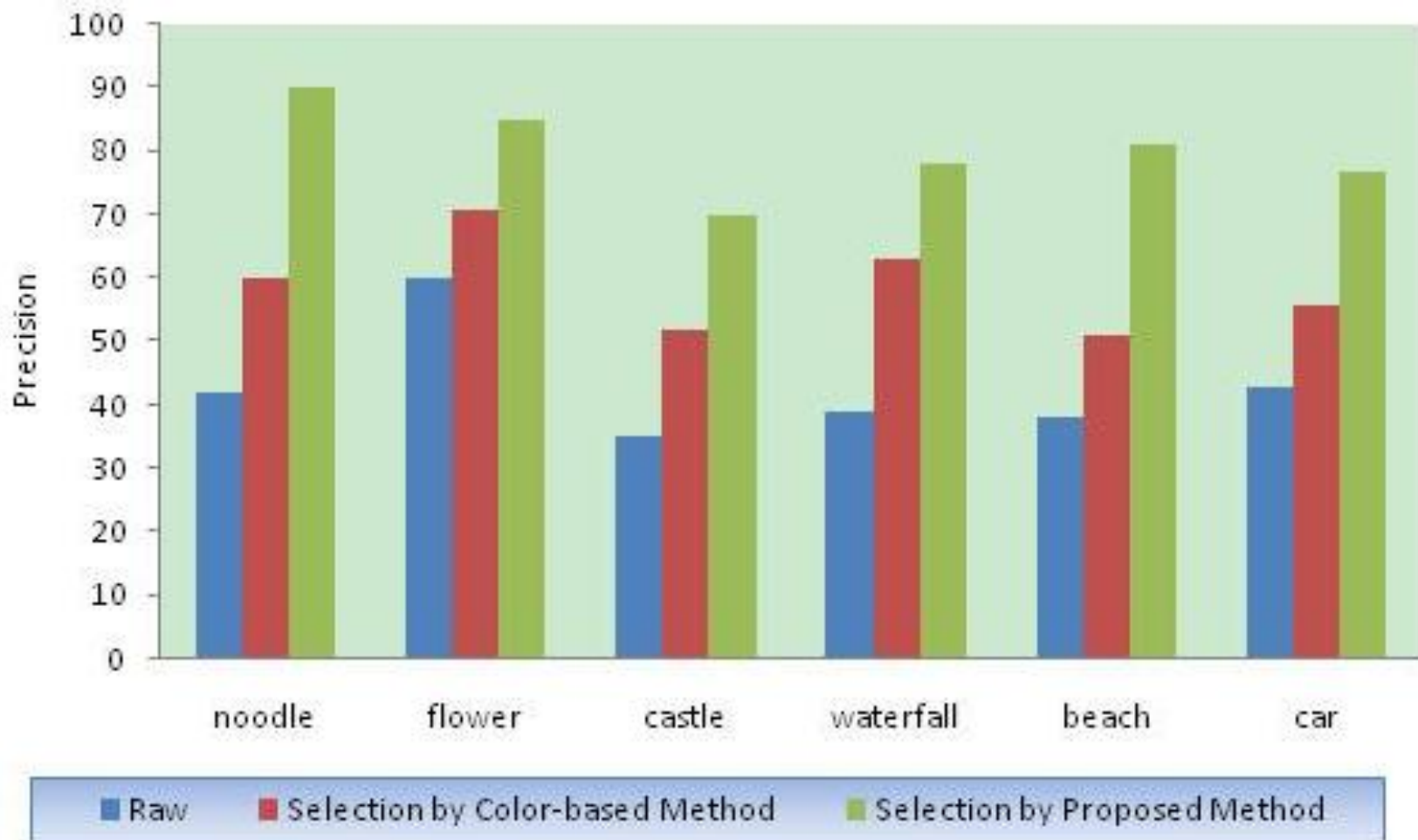
- **Detect canonical photos of a specific object on each place over the world**
 - **Eg.) "noodle" : Chinese noodle in Asia, spaghetti in Europe**
 - **Do not limit to only scene of specific places or landmarks. Any objects are our targets !**
- **The method is not very novel, but the objective of the work is very novel.**
 - **Novel application for geotagged photo DB.**

5. [Part 2] Results

Experimental Results

- **“noodle”, “flower”, “castle”, “waterfall”, “beach”, “car”**
 - ✓ **For each concept , collect about 2000 geo-tagged photos from Flickr distributed evenly in the world wide areas**
- **Quantitative evaluation for the 1st step**
 - ✓ **Evaluation on our proposed method for extracting the most relevant photos**
 - ✓ **Precision and Recall**
 - ✓ **Color-histogram-based method for comparison**
- **Examples of regional representative photos**

Quantitative Evaluation for 1st step



Average recall : 73.0%

[Example of results] "noodle"

[Please choose your options] Keyword: noodle District: [v] [Jump] [Animation Control] [Auto Play] [Stop] [Continue]

Representative photos for "noodle"

© 2008 Yanai Lab., Department of Computer Science, The University of Electro-Communications, Tokyo, Japan

[Please choose your options] Keyword: noodle District: [v] [Jump] [Animation Control] [Auto Play] [Stop] [Continue]

Representative photos for "noodle"

© 2008 Yanai Lab., Department of Computer Science, The University of Electro-Communications, Tokyo, Japan

[Please choose your options] Keyword: noodle District: [v] [Jump] [Animation Control] [Auto Play] [Stop] [Continue]

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Representative photos for "noodle"

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[Please choose your options] Keyword: noodle District: [v] [Jump] [Animation Control] [Auto Play] [Stop] [Continue]

Representative photos for "noodle"

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[Example of results] "noodle"

[Please choose your options] Keyword: District: [Animation Control]

Map Satellite Hybrid Terrain

Representative photos for "noodle"

The screenshot shows a web application interface for searching for 'noodle'. At the top, there is a search bar with the keyword 'noodle' and a 'District' dropdown set to '3'. To the right are 'Animation Control' buttons: 'Auto Play', 'Stop', and 'Continue'. Below the search bar is a map of Europe with several location pins. A tooltip is visible over a location in Italy, showing a photo of spaghetti and the coordinates [41.900659, 12.514436]. On the right side of the map, there is a section titled 'Representative photos for "noodle"' which contains a grid of 40 small images of various noodle dishes. At the bottom of the map, there is a copyright notice: '© 2008 Yanai Lab., Department of Computer Science, The University of Electro-Communications, Tokyo, Japan'.

Taiwan spaghetti photos in the European area
Japan

[Example of results] "flower"



[Example of results] “flower”

[Please choose your options] Keyword: District: [Animation Control]

Map Satellite Hybrid Terrain

[11/68]
[52.269316, 4.546076]

Representative photos for "flower"

The screenshot displays a web-based interface for searching and visualizing flower data. At the top, there is a search bar with the keyword "flower" and a "District" dropdown set to "2". To the right, there are "Animation Control" buttons: "Auto Play", "Stop", and "Continue". The main area is split into two panels. The left panel shows a map of Europe with numerous blue location pins. A callout window is open over a pin in the Netherlands, displaying the coordinates [52.269316, 4.546076] and a small image of red tulips. The right panel, titled "Representative photos for 'flower'", contains a grid of 20 small images showing various colorful flowers. At the bottom, there is a copyright notice: "© 2008 Yanai Lab., Department of Computer Science, The University of Electro-Communications, Tokyo, Japan".

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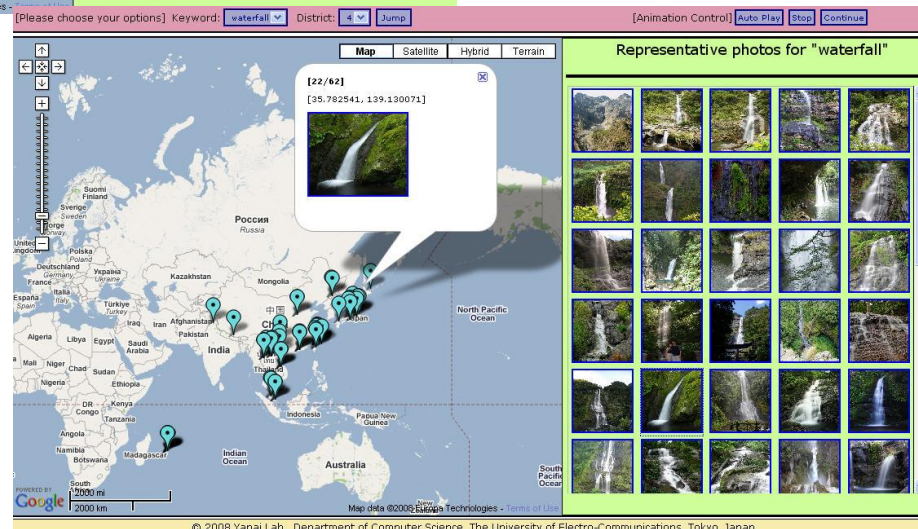
Netherlands national flower is the “Tulip”

[Example of results] “waterfall”



“Powerful” waterfalls
in South America

“Beautiful” waterfalls
in Asia



Wedding cake !



Figure 12: "Wedding cake" in Mid US. Tall cakes are common. This is five-layered.



Figure 13: "Wedding cake" in Europe. They are much shorter and simpler than US.

6. Conclusions

Conclusions

- ***In this paper, we pointed out that image sets associated with the same concepts are variable depending on locations***
- ***To analysis that, we proposed to use geotagged photos on the Web.***
 1. ***Entropy-based analysis***
 - ***Image region entropy and geo-location entropy***
 2. ***A system to help detect “cultural differences” by selecting representative photos for each location***

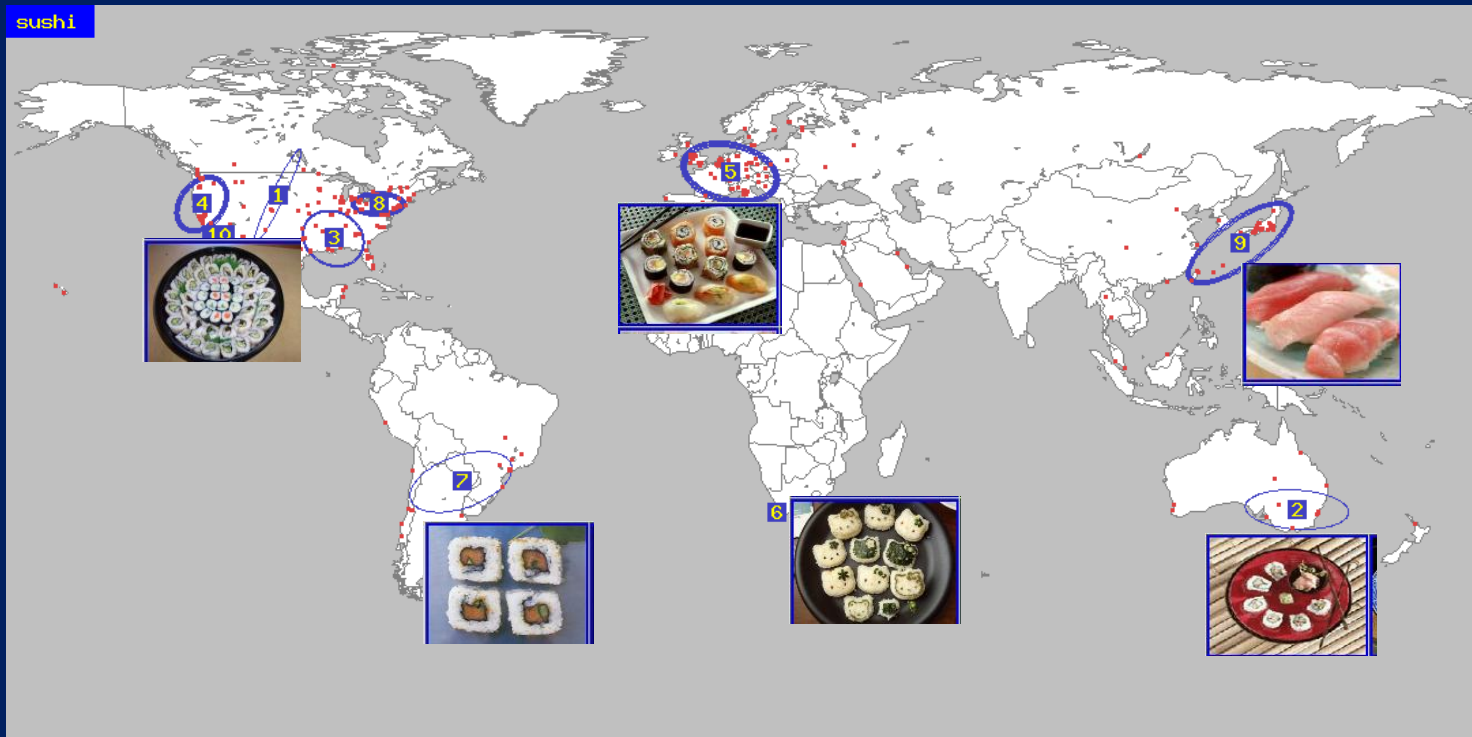
Future work

- **Use cross-language query to get images**
 - **Actually the obtained results are biased by English-culture, because we used only English words when gathering geotagged images from Flickr.**
- **Discover (subtle) cultural differences automatically (*hopefully hard for human*)**
- **Extensive study on cultural differences using a large-scale geotagged photo DB**

Towards location(culture) – specific image recognition

- **This analysis will help build location (culture) – specific object / scene recognition systems.**
 - **For location – dependent concepts, specific training image sets are needed, while for global concepts global image sets are OK.**
 - **To build systems for Japanese people, a special training set for “Suishi” is needed.**
 - **For people in Santorini, specific image sets for “house” and “building” might be needed.**

Thank you for your attention !



3. *Methods*